Design Requirement			
Date:	10/18/2021		
Design Project Title:	Deliveroid		
Team Name:	Tempest Team		
Team Advisor	Dr. Kim		
Team Assistant			
Project's Long Term Goal	To create a robot that will autonomously deliver items to multiple floors and buildings		
Project's Current Academic Year Goal	2022		
Team Members (Senior Design Class)	Michael Vaughan, Forzando Mebane, Williams Obidike		
Team Members (Others)			
1-Sentence Problem Statement	Getting up from your desk to transfer documents has developed the need to create a robot that will autonomously transfer said documents so that you will not get disturbed from your work.		
Requirements	Items	Descriptions	
1. Product Specification (or <u>Software</u> <u>Requirement</u> <u>Specification</u>)	2D Map	Simulation area mapping and measurement	
	Arduino code	Meshing map with motor code	
	Arduino Uno	For embedded development of device functions	
	3D Model	Frame assembly of the robot	

	ESP8266 wifi module	Network features
2. Contraints	Cost	Under \$200
	Time	Deadline: April 2022
	Environmental and Social Responsibility	Use recycled parts Electric motor Power efficient

3. Compliance to regulations and standards

Standard / Rugulations	ISO 13849-1 Safety of machinery and parts of control system
	International Electrotechnical Commission (IEC) 61000-4-2 Electrostatic Discharge Immunity Test
Standard	
Patent Intellectual Property	Delivery robot product